

# Discrete-Time Bases and Filter Banks

“What is more beautiful than the Quincunx,  
which, from whatever direction you look is correct?”

Quintilian 

**Series expansions of discrete-time signals**

**Two-channel filter banks**

**Tree-structured filter banks**

**Multichannel filter banks**

**Pyramids and overcomplete expansions**

**Multidimensional filter banks**

**Transmultiplexers**

# Introduction

## Focus

- series expansions of discrete-time signals
- many signals inherently discrete time need to manipulate them
- most signals end up being processed in discrete-time
- some construction fundamental for continuous-time wavelets
- computational tool for continuous-time signals
- computation basis for algorithms

# Series expansions of discrete-time signals

## Orthonormal

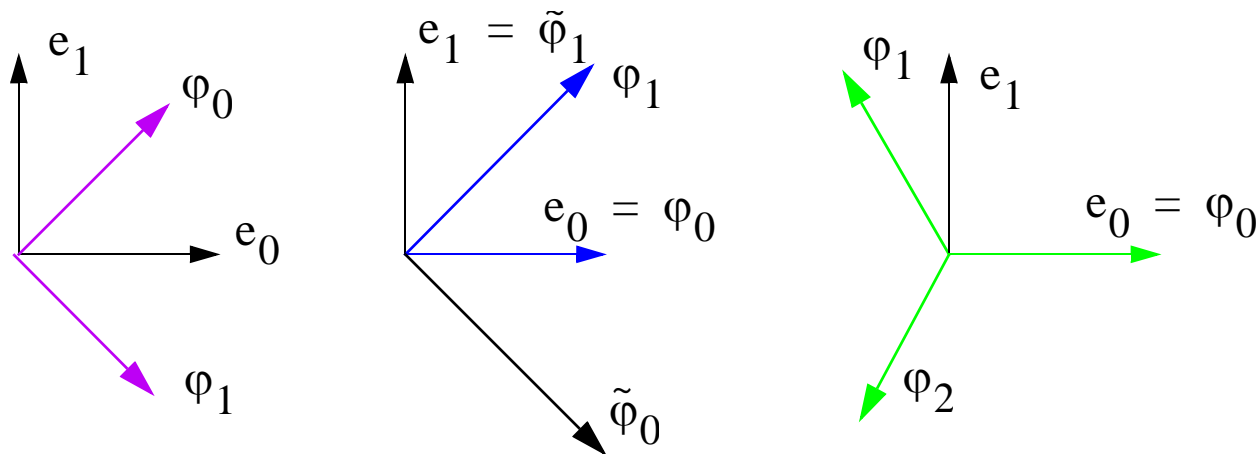
- basis functions are orthonormal
- conservation of energy

## Biorthogonal

- basis functions are biorthogonal

## Overcomplete

- redundant sets of functions



## Series expansions of discrete-time signals... ... orthonormal

### Expansion

$$x[n] = \sum_k \langle \phi_k[l], x[l] \rangle \phi_k[n] = \sum_k X[k] \phi_k[n]$$

### Transform coefficients

$$X[k] = \langle \phi_k[l], x[l] \rangle = \sum_l \phi_k^*[l] x[l]$$

### Orthonormality constraint

$$\langle \phi_k[n], \phi_l[n] \rangle = \delta[k - l]$$

### Conservation of energy

$$\|x\|^2 = \|X\|^2$$

## Series expansions of discrete-time signals... ... biorthogonal

### Expansion

$$x[n] = \sum_k \langle \phi_k[l], x[l] \rangle \tilde{\phi}_k[n] = \sum_k \tilde{X}[k] \tilde{\phi}_k[n]$$

$$x[n] = \sum_k \langle \tilde{\phi}_k[l], x[l] \rangle \phi_k[n] = \sum_k X[k] \phi_k[n]$$

### Transform coefficients

$$\begin{aligned} \tilde{X}[k] &= \langle \phi_k[l], x[l] \rangle = \sum_l \phi_k^*[l] x[l], \\ X[k] &= \langle \tilde{\phi}_k[l], x[l] \rangle = \sum_l \tilde{\phi}_k[l] x[l] \end{aligned}$$

### Biorthogonality constraint

$$\langle \phi_k[n], \tilde{\phi}_l[n] \rangle = \delta[k - l]$$

### Conservation of energy

$$\|x\|^2 = \langle X[k], \tilde{X}[k] \rangle$$

## Series expansions of discrete-time signals ... ... why not Fourier?

### **Possibility: discrete-time Fourier series**

- deals with limited signal space (periodic or finite)

### **Block discrete Fourier transform**

- deals with arbitrary signals
- transform is periodically time varying
- certain time locality is achieved
- abrupt changes between intervals

### **Look for **structured** expansions**

- simple characterization
- some localization in time and frequency
- certain invariance properties

## Discrete-time bases from filter banks

**These are structured bases for  $L_2(\mathfrak{R})$  where a finite set of  $N$  filters generates the basis.**

**Result:** Given  $N$  filters with impulse responses  $g_i[n]$  the set

$$\{g_0[n - Nk], g_1[n - Nk], \dots, g_{N-1}[n - Nk]\}_{k \in \mathbb{Z}}$$

is a basis for  $l_2(\mathfrak{T})$ .

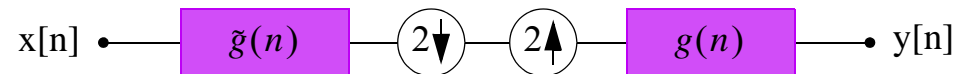
**Result:** Given 2 filters with impulse responses  $g_i[n]$  the set

$$\{g_0[n - 2k], g_1[n - 2k]\}_{k \in \mathbb{Z}}$$

is a basis for  $l_2(\mathfrak{T})$ .

## Orthogonal filter banks... ... a comprehensive example

**Recall P**



where  $\langle g[n], g[n-2k] \rangle = \delta_k$  and  $\tilde{g}[n] = g[-n]$

**A. P is an orthogonal projection onto the subspace V**

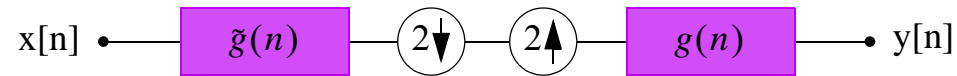
$$V = \text{span}\{g[n-2k]\}_{k \in \mathbb{Z}}$$

**Proof:** From background material and  $y[n] = \sum_i \alpha_i \cdot g[n-2i]$

- $\{g[n-2k]\}_{k \in \mathbb{Z}}$  is an orthonormal basis for V



## B. Projection onto V



$$y[n] = \sum_i \alpha_i \cdot g[n - 2i]$$

$$\alpha_i = \langle g[k - 2i], x[k] \rangle_k$$

- convolution with  $\tilde{g}[n]$  is equivalent to inner product with  $g[n]$

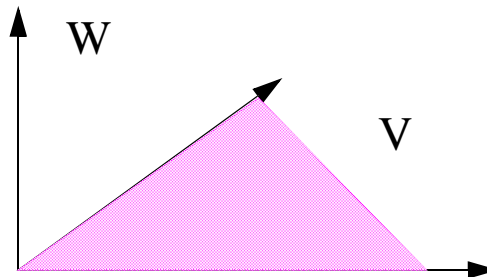
**C. Orthogonal complement  $W$  to  $V$  in  $l_2(\mathfrak{T})$  :**

$$l_2(Z) = V \oplus W \quad V \perp W$$

- find  $g^\perp[n]$  such that

$$\langle g^\perp[n], g[n-2k] \rangle_n = 0 \quad k \in \mathbb{Z}$$

- completeness: span must be equal to  $l_2(\mathfrak{T})$



## D. Ansatz

$$g^\perp[n] = (-1)^n \cdot g[-n + L - 1]$$

- $g[n]$  is FIR of length  $L$ ,  $L$  is even

### Example:

$$g[n] = [a, b, c, d] \quad g^\perp[n] = [d, -c, b, -a]$$

Show that:

$$\langle g^\perp[n], g[n - 2k] \rangle_n = 0 \quad k \in \mathbb{Z}$$

Then:

$$\begin{bmatrix} c & d & 0 & 0 \\ a & b & c & d \\ 0 & 0 & a & b \end{bmatrix} \cdot \begin{bmatrix} d \\ -c \\ b \\ -a \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

**General proof: similar, use pairwise cancellation**

### E. Completeness:

- Now,  $g^\perp[n]$  and its shift by 2 are orthogonal, which follows from the orthogonality of  $g[n-2k]$

So we have an orthonormal basis for  $W$ , and we know from above that  $V \perp W$ . But do we have:

$$l_2(\mathfrak{T}) = V \oplus W?$$

**Proof:** Intuition:  $l_2(\mathfrak{T})$  splits into two halves,  $V$  and  $W$

**Proof:** Clean proof:

Use Parseval and show that

$$\|x\|^2 = \|x_V\|^2 + \|x_W\|^2$$

for all  $x \in l_2(\mathfrak{T})$ .

- this will be shown later using paraunitary matrices

## **F. How to find such $g[n]$ 's?**

$$\langle g[n], g[n-2k] \rangle_n = \delta_k$$

- this is simply the autocorrelation of  $g[n]$  evaluated at even lags, or subsampled by 2.

**In z-transform domain, the autocorrelation is**

$$\langle g[n], g[n-i] \rangle_n \Leftrightarrow G(z) \cdot G(z^{-1})$$

**The first condition becomes equivalent to**

$$\frac{1}{2}[G(z) \cdot G(z^{-1}) + G(-z) \cdot G(-z^{-1})] = 1$$

**Introducing  $P(z) = G(z) \cdot G(z^{-1})$  we need**

- a symmetric positive definite polynomial  $P(z)$  satisfying  $P(z) + P(-z) = 2$

**By spectral factorization, we get a possible  $G(z)$**

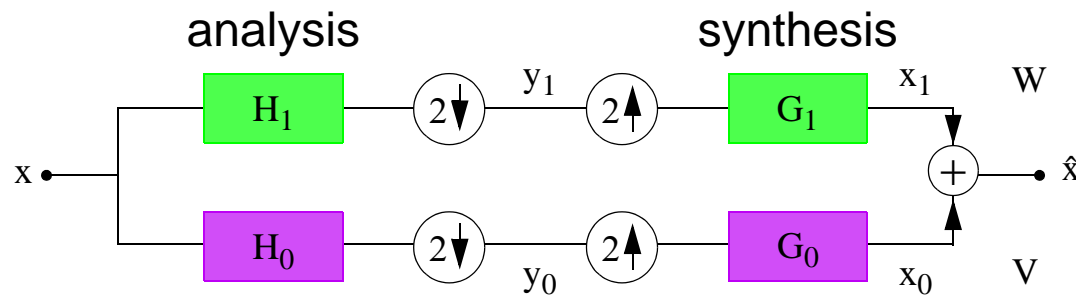
## G. Putting it all together!

- $\{g[n-2k]\}_{k \in \mathbb{Z}}$  is an orthonormal basis for  $V$
- $\{g^\perp[n-2k]\}_{k \in \mathbb{Z}}$  is an orthonormal basis for  $W$
- $l_2(\mathfrak{T})$  splits into  $V$  and  $W$

### Use assignment:

- synthesis filters:  $g_0[n] = g[n]$        $g_1[n] = g^\perp[n]$
- analysis filters:  $h_0[n] = \tilde{g}[n]$        $h_1[n] = \tilde{g}^\perp[n]$

**We have developed filter banks as orthonormal expansions and projections into complementary subspaces**



## H. Time domain view

Example:  $L = 4$

$$g[n] = [a, b, c, d] \quad g^\perp[n] = [d, -c, b, -a]$$

$$\bullet \text{ analysis: } \begin{bmatrix} \dots \\ y_0[0] \\ y_1[0] \\ y_0[1] \\ y_1[1] \\ \dots \end{bmatrix} = \begin{bmatrix} a & b & c & d & 0 & 0 & 0 & 0 \\ d & -c & b & -a & 0 & 0 & 0 & 0 \\ 0 & 0 & a & b & c & d & 0 & 0 \\ 0 & 0 & d & -c & b & -a & 0 & 0 \\ 0 & 0 & 0 & 0 & a & b & c & d \\ 0 & 0 & 0 & 0 & d & -c & b & -a \end{bmatrix} \cdot \begin{bmatrix} \dots \\ x[0] \\ x[1] \\ x[2] \\ \dots \end{bmatrix}$$

$$y = T \cdot x$$

- synthesis:  $x = T^T \cdot y$
- in this orthonormal case, we have:

$$T \cdot T^T = T^T \cdot T = I$$

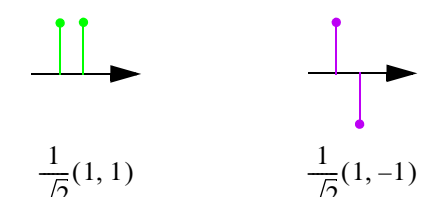
## Haar expansion and its FB implementation

$$\varphi_{2k}[n] = \begin{cases} \frac{1}{\sqrt{2}} & \text{for } n = 2k, 2k+1 \\ 0 & \text{otherwise} \end{cases}$$

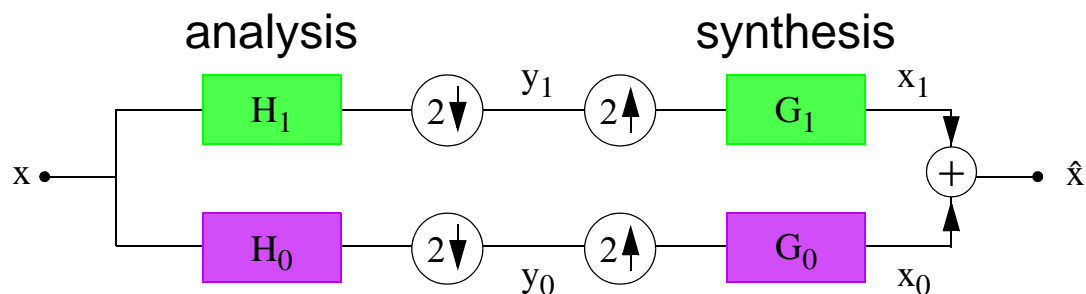
$$\varphi_{2k+1}[n] = \begin{cases} \frac{1}{\sqrt{2}} & \text{for } n = 2k \\ -\frac{1}{\sqrt{2}} & \text{for } n = 2k+1 \\ 0 & \text{otherwise} \end{cases}$$

$h_0[n] = \varphi_0[-n]$     $h_1[n] = \varphi_1[-n]$   
 $g_0[n] = \varphi_0[n]$     $g_1[n] = \varphi_1[n]$

**average**                      **difference**



$\frac{1}{\sqrt{2}}(1, 1)$                        $\frac{1}{\sqrt{2}}(1, -1)$

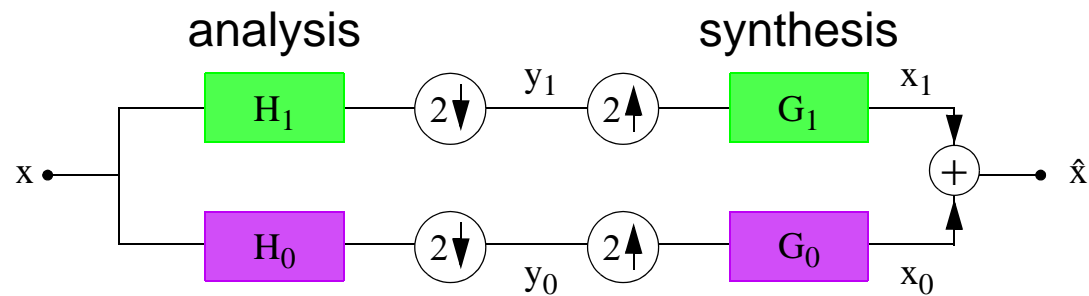




## Sinc expansion and its FB implementation

$$\phi_{2k}[n] = \frac{1}{\sqrt{2}} \frac{\sin \pi \frac{(n-2k)}{2}}{\pi \frac{(n-2k)}{2}}$$

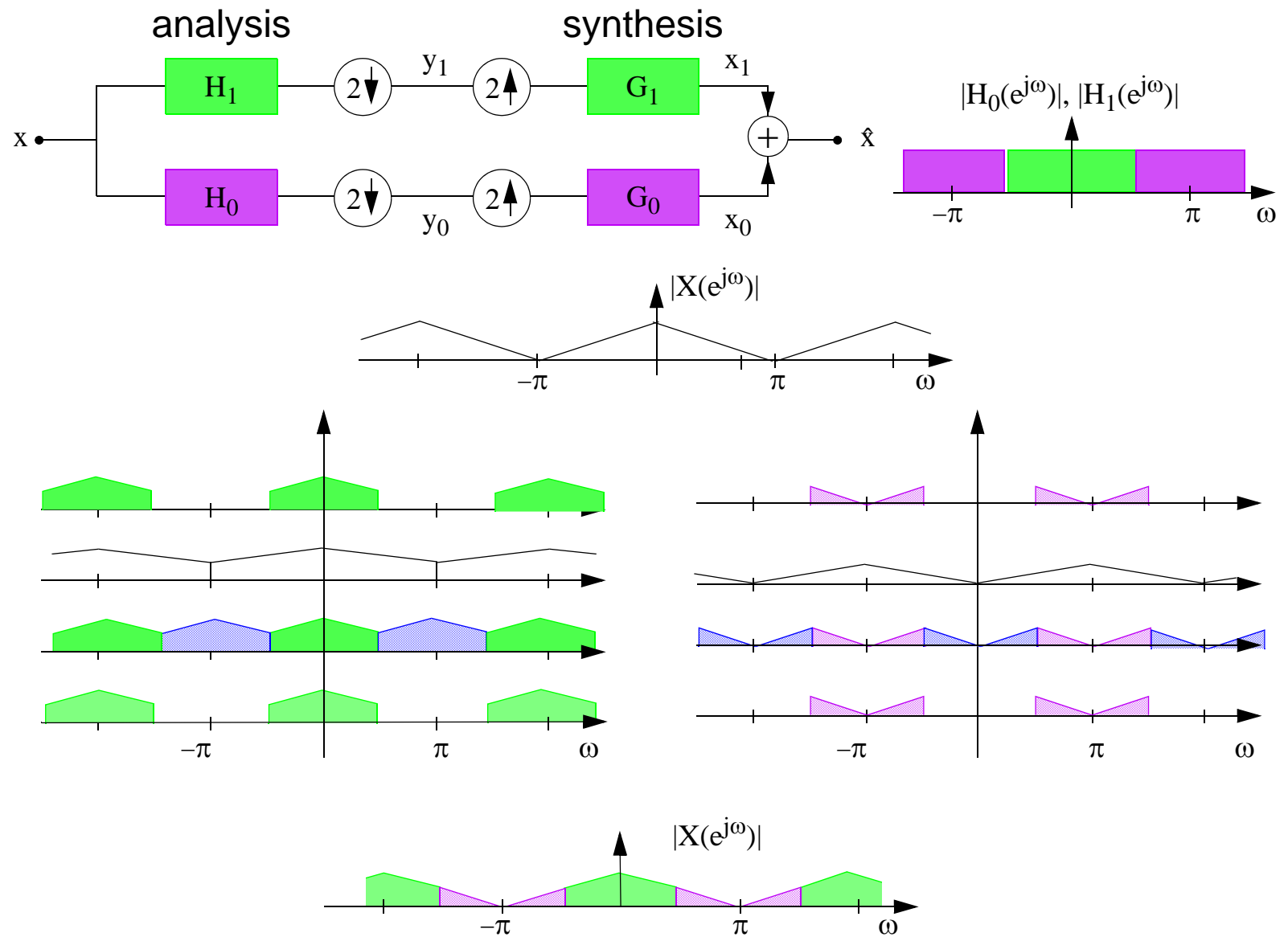
$$\phi_{2k+1}[n] = (-1)^{n-2k} g_0[-n+2k+1]$$



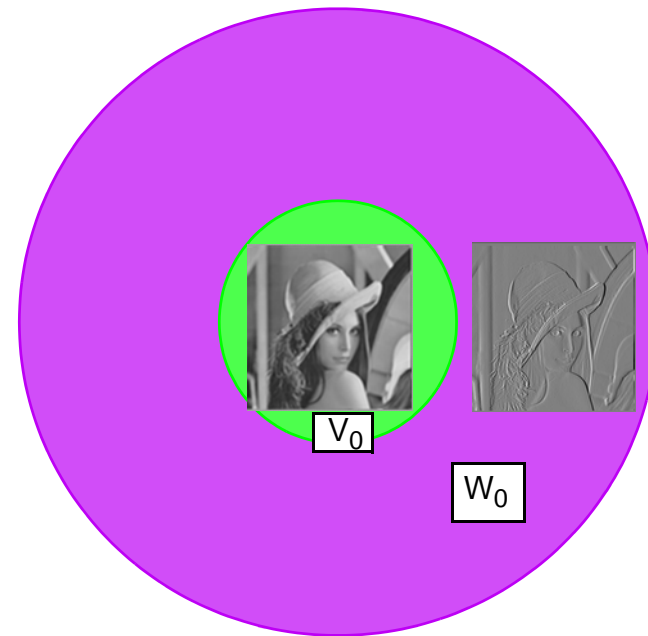
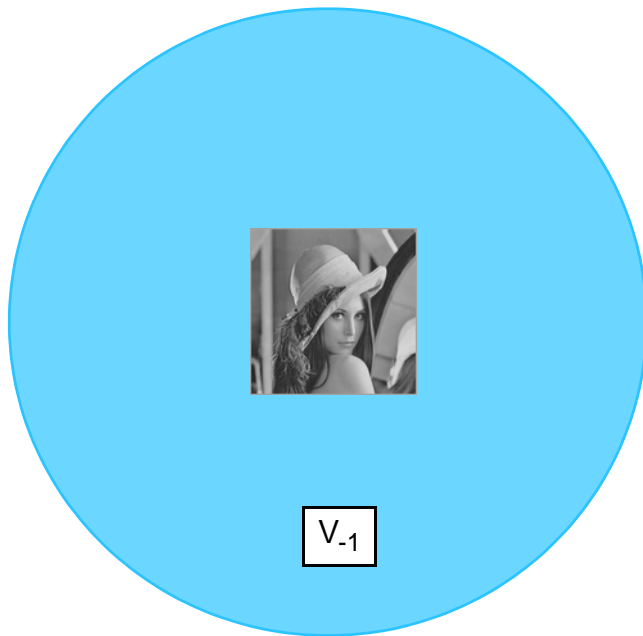
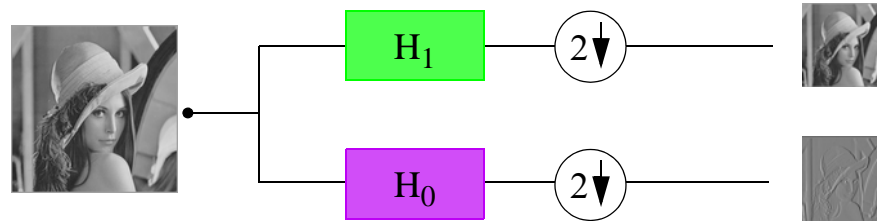
$$h_0[n] = \phi_0[-n] \text{ and } h_1[n] = \phi_1[-n]$$

$$g_0[n] = \phi_0[n] \text{ and } g_1[n] = \phi_1[n]$$

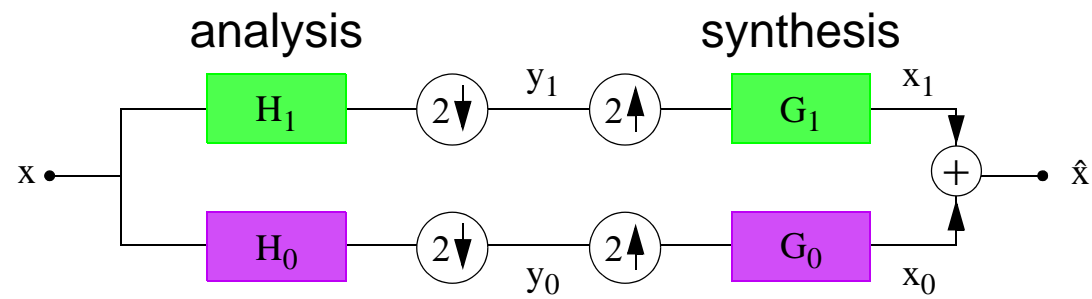
## Two-channel filter banks



## MR concept underlying filter banks

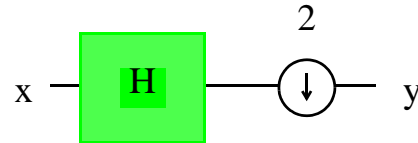


## Analysis methods for filter banks



- time domain
- polyphase domain
- modulation domain

## Time-domain analysis



$$\begin{bmatrix} \dots \\ y[0] \\ y[1] \\ \dots \end{bmatrix} = \begin{bmatrix} \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & h[L-1] & h[L-2] & h[L-3] & h[L-4] & \dots \\ \dots & 0 & 0 & h[L-1] & h[L-2] & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{bmatrix} \begin{bmatrix} \dots \\ x[0] \\ x[1] \\ \dots \end{bmatrix}$$

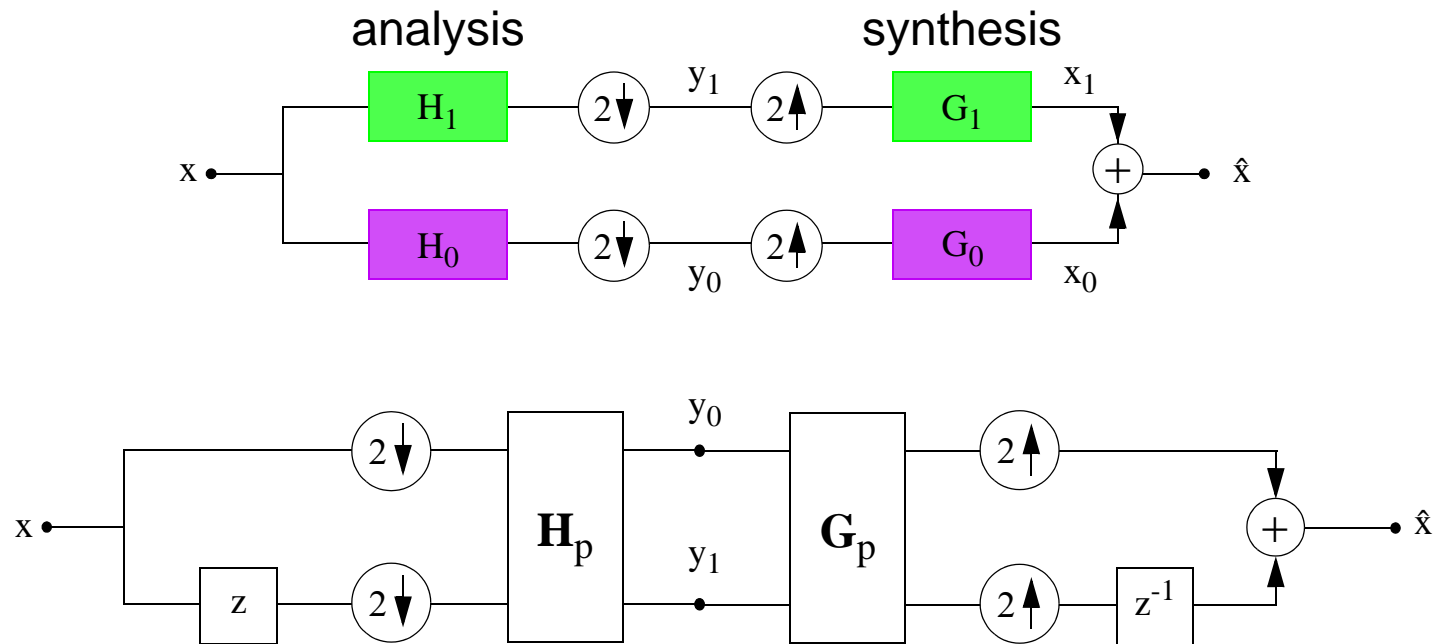
**Perfect reconstruction:**

$$G_0 H_0 + G_1 H_1 = I$$

**Orthogonal system:**

$$(H_0)^* H_0 + (H_1)^* H_1 = I \quad G_0 = (H_1)^*$$

## Polyphase-domain analysis



**Polyphase components:**  $Y(z) = \text{IPT}(z)G_p(z^2)H_p(z^2)x_p(z^2)$   
 • even and odd subsequences  $x[2n]$  and  $x[2n + 1]$

**Perfect reconstruction:**  $G_p H_p = I$

**Orthogonal system:**  $(H_p)^* H_p = I$   $G_p = (H_p)^*$   
Filter banks - 22

## Polyphase-domain analysis...

### ... key results

**Result:** If  $G_p(z)$  is paraunitary, choose:

$$H_p(z) = G_p^T(z^{-1})$$

to get perfect reconstruction.

**Proof:** By inspection.

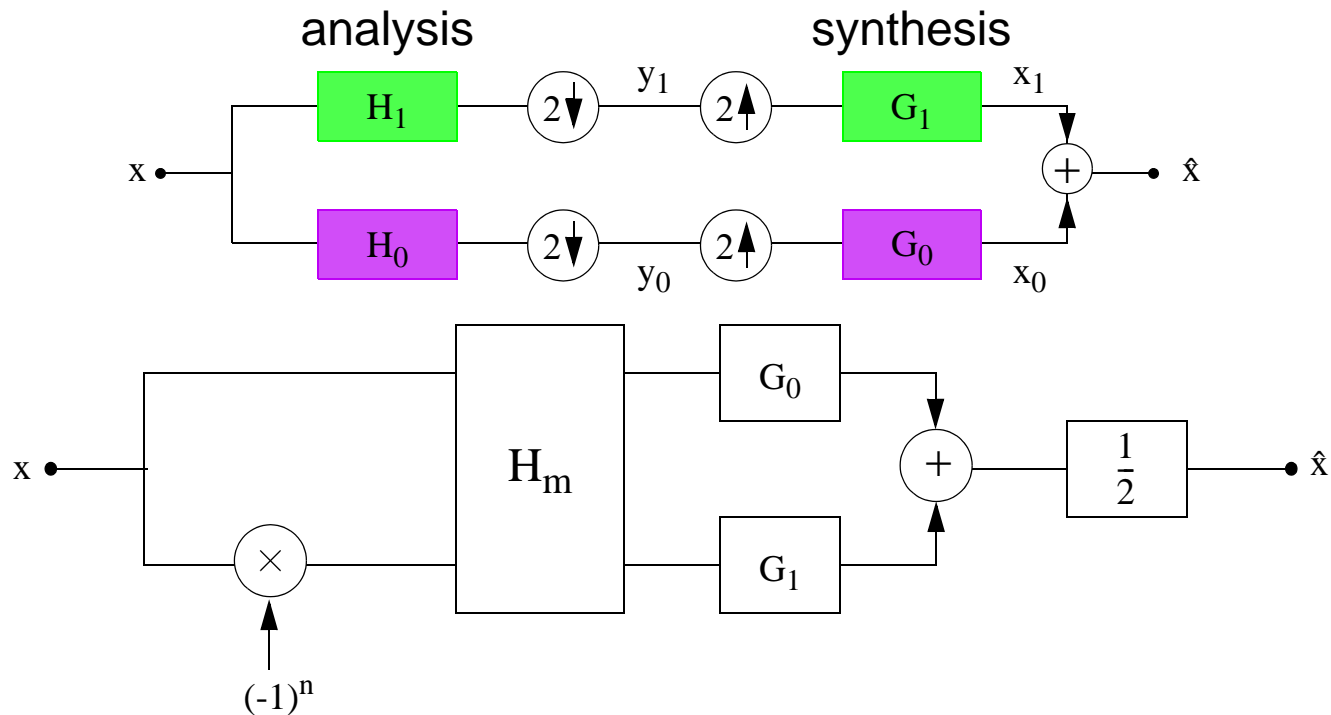
**Result:**  $G_p(z)$  paraunitary and  $H_p(z)$  as above lead to an orthonormal expansion

**Proof:** Parseval's equality.

**Result:** Choosing  $g[n]$  orthonormal to its even translates, and the other filter as usual (ansatz) leads automatically to a paraunitary polyphase matrix

**Proof:** By inspection.

## Modulation-domain analysis



$$Y(z) = \frac{1}{2} \begin{bmatrix} G_0(z) & G_1(z) \end{bmatrix} \begin{bmatrix} H_0(z) & H_0(-z) \\ H_1(z) & H_1(-z) \end{bmatrix} \begin{bmatrix} X(z) \\ X(-z) \end{bmatrix}$$

**Aliasing component:**

$X(-z)$

**Perfect reconstruction:**

$$GH_m = \begin{bmatrix} 2 & 0 \end{bmatrix}$$

**Orthogonal system:**

$$H^*H = I$$

$$G = H^*$$



## Aliasing cancellation:

**I/O relationship**

$$Y(z) = \frac{1}{2} \begin{bmatrix} G_0(z) & G_1(z) \end{bmatrix} \begin{bmatrix} H_0(z) & H_0(-z) \\ H_1(z) & H_1(-z) \end{bmatrix} \begin{bmatrix} X(z) \\ X(-z) \end{bmatrix}$$

**To guarantee aliasing cancellation**

$$[G_0(z), G_1(z)] \perp [H_0(-z), H_1(-z)]$$

or

$$[G_0(z), G_1(z)] = \alpha(z) \cdot [H_1(-z), -H_0(-z)]$$

Then

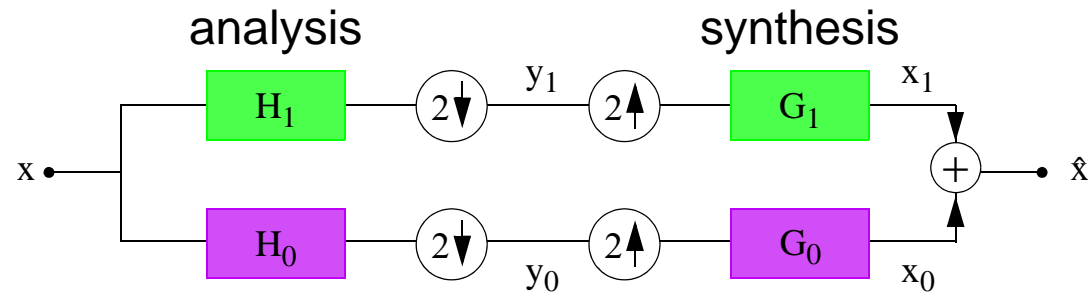
$$Y(z) = \frac{1}{2} \cdot \alpha(z) \cdot [H_0(z)H_1(-z) - H_0(-z)H_1(z)] \cdot X(z)$$

that is,  $X(-z)$  is automatically cancelled,  
independent of the filters  $H_0(z)$ ,  $H_1(z)$  used.

## Quadrature Mirror Filters (QMF)

**Earliest example of aliasing cancellation,  
very important in speech compression**

[Esteban-Galand, 1976]



Thus

$$Y(z) = \frac{1}{2} \cdot \begin{bmatrix} H(z) & -H(-z) \end{bmatrix} \cdot \begin{bmatrix} H(z) & H(-z) \\ H(-z) & H(z) \end{bmatrix} \cdot \begin{bmatrix} X(z) \\ X(-z) \end{bmatrix}$$

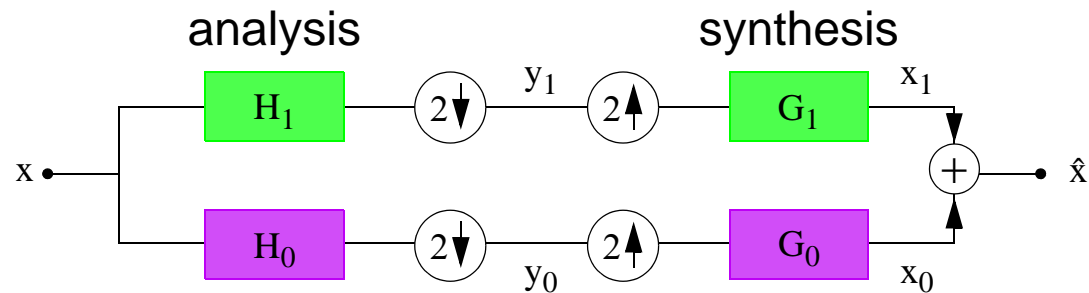
**or**

$$Y(z) = \frac{1}{2} \cdot [H^2(z) - H^2(-z)] \cdot X(z)$$

- $H(z)$  should be linear phase and even length

## Orthogonal FIR filter banks

- synthesis filters the same as analysis (within reversal)
- **no linear phase** in this case (except trivial Haar filters)

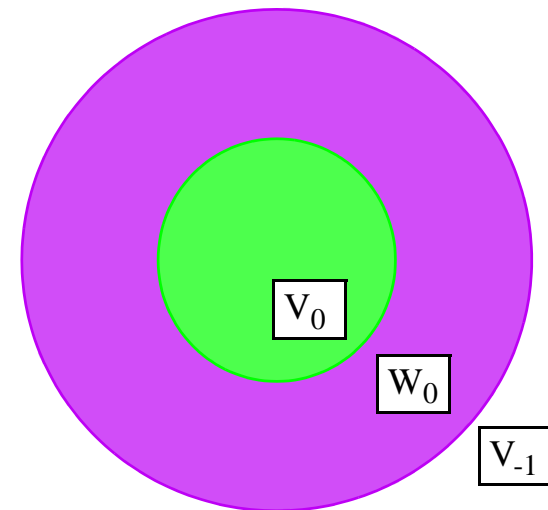


### Split the space in two:

- coarse approximation and added detail
- $V_{-1} = V_0 \oplus W_0$  and  $V_0 \perp W_0$

$V_{-1}$ : **space of sequences**  $l_2(\mathfrak{T})$

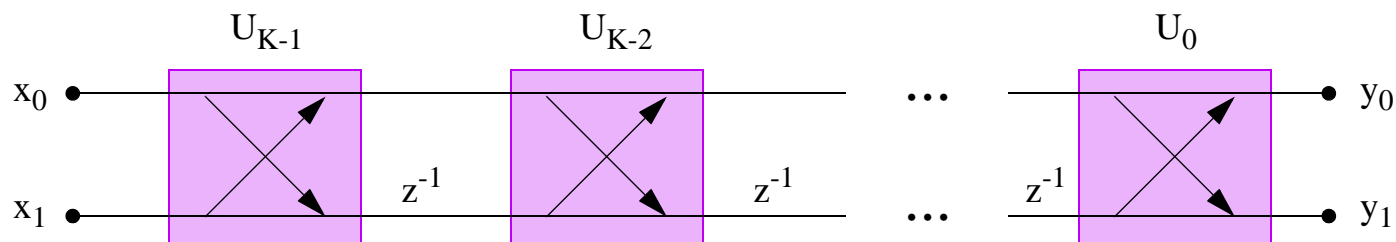
- rows of matrix  $H_0$ : basis for  $V_0$
- rows of matrix  $H_1$ : basis for  $V_1$
- rows of  $H_0$  and  $H_1$ : basis for  $V_{-1}$



## Design methods for orthogonal filter banks... ... based on lattice structures

[Vaidyanathan & Hoang]

- well-conditioned
- factorization of a paraunitary matrix



$$H_p(z) = R_0 \cdot \prod_{i=1}^{N-1} \begin{bmatrix} 1 & 0 \\ 0 & z^{-1} \end{bmatrix} \cdot R_i, \text{ with } R_i = \begin{bmatrix} \cos(\alpha_i) & -\sin(\alpha_i) \\ \sin(\alpha_i) & \cos(\alpha_i) \end{bmatrix}$$

- all orthogonal solutions can be reached using this cascade

## Design methods for orthogonal filter banks... ... based on spectral factorization

- numerically ill-conditioned
- like “taking a square root”

### [Smith&Barnwell]

- PR condition for orthogonal filter banks

$$H_0(z)\tilde{H}_0(z) + H_0(-z)\tilde{H}_0(-z) = P(z) + P(-z) = 2$$

- even subsequence is  $\delta[n]$
- find such an autocorrelation sequence  $P(z)$
- factor into roots  $(\alpha, \frac{1}{\tilde{\alpha}})$  and assign from each pair one to  $H(z)$

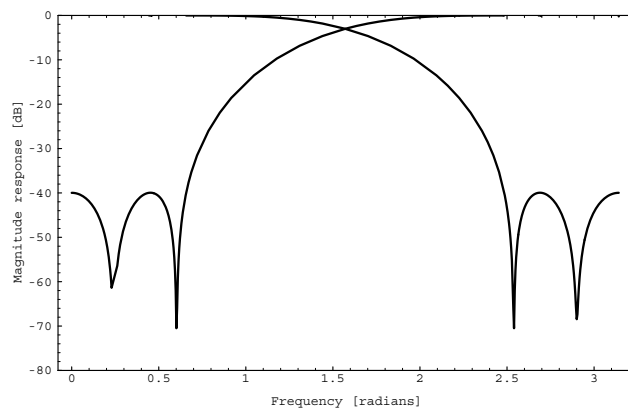
## **Design methods for orthogonal filter banks... ... based on spectral factorization**

**[Daubechies]: minimum phase, designed to obtain wavelets**

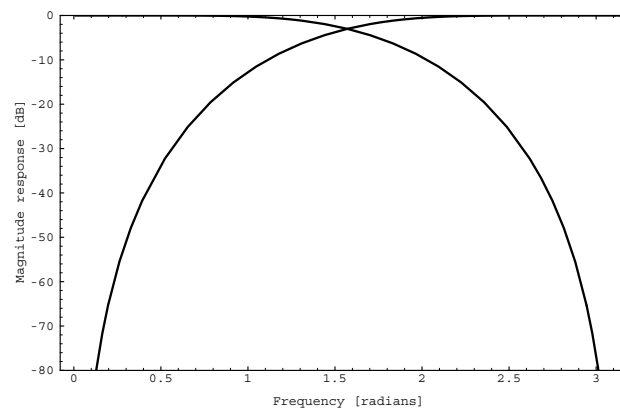
- repeat the Smith & Barnwell procedure
- impose maximum number of zeros at  $\pi$
- for the rest, take factors only inside unit circle

**Consequently, these filters are often called “discrete wavelets”**

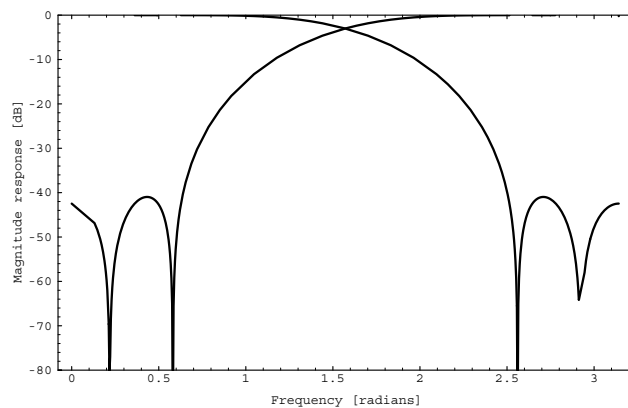
## Design methods for orthogonal filter banks ... ... example of length 8



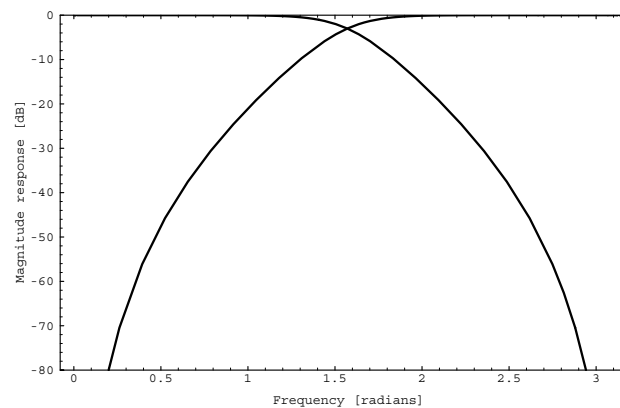
Smith & Barnwell



Daubechies



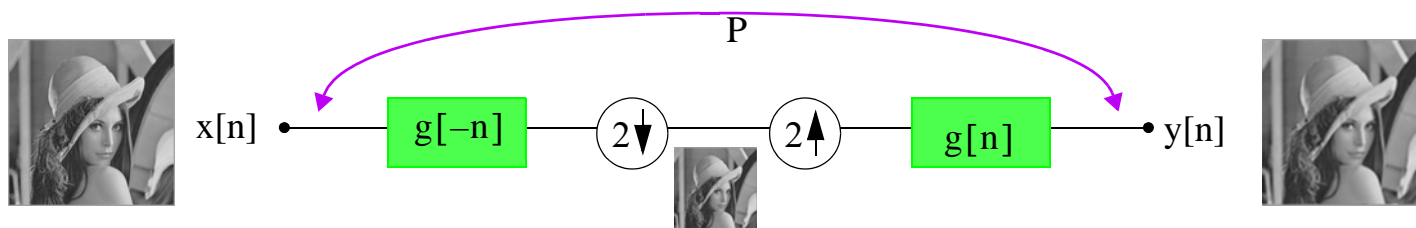
Vaidyanathan & Hoang



Butterworth  
N = 4

## Orthogonal filter banks ... ... projection view

### Recall



with  $\langle g[n], g[n-2k] \rangle = \delta_k$ , then

$P$  is an orthogonal projection

or, in other words,

$P$  maps  $l_2(\mathfrak{T})$  into  $V$  subspace of  $l_2(\mathfrak{T})$



## Design methods for biorthogonal filter banks

Analysis and synthesis filters are not the same anymore

Particular case of interest: linear phase

[Vetterli & LeGall]: lattice structure

$$H_p(z) = R_0 \cdot \prod_{i=1}^{N-1} \begin{bmatrix} 1 & 0 \\ 0 & z^{-1} \end{bmatrix} \cdot R_i, \text{ with } R_i = \begin{bmatrix} 1 & \alpha_i \\ \alpha_i & 1 \end{bmatrix}$$

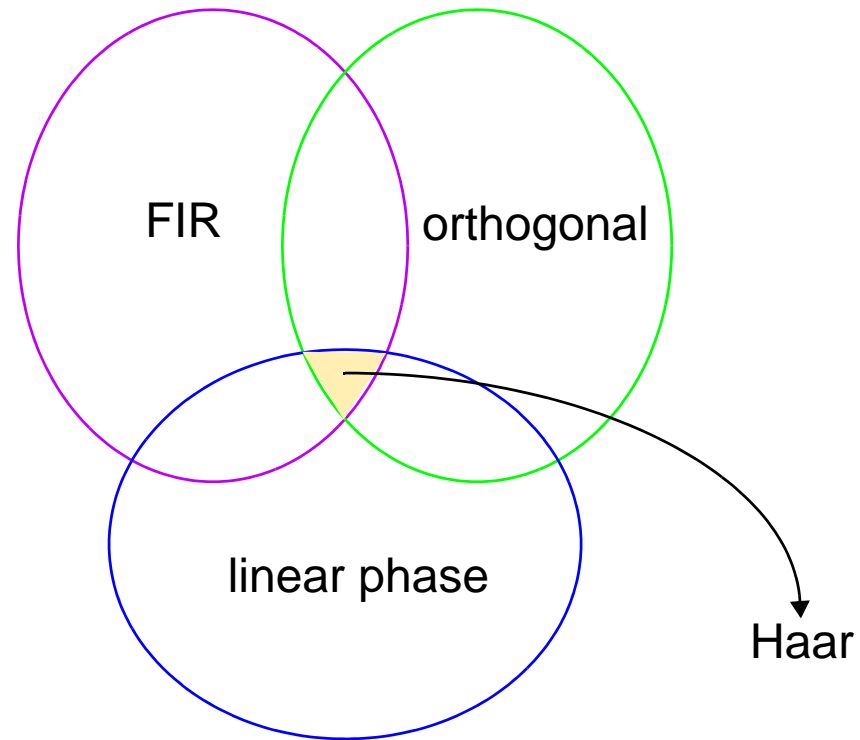
[Vetterli & Herley]:

- PR condition for biorthogonal filter banks

$$H_0(z)\tilde{H}_1(z) + H_0(-z)\tilde{H}_1(-z) = P(z) + \tilde{P}(z) = 2$$

- find such a  $P(z)$
- factor into LP factors and distribute between  $H_0(z)$  and  $H_1(z)$

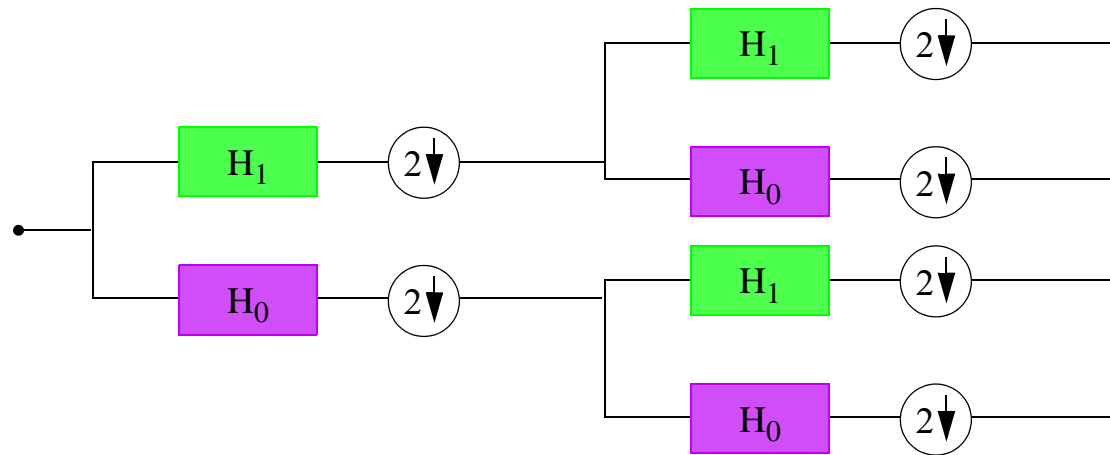
## Two-channel filter banks ... ... summary



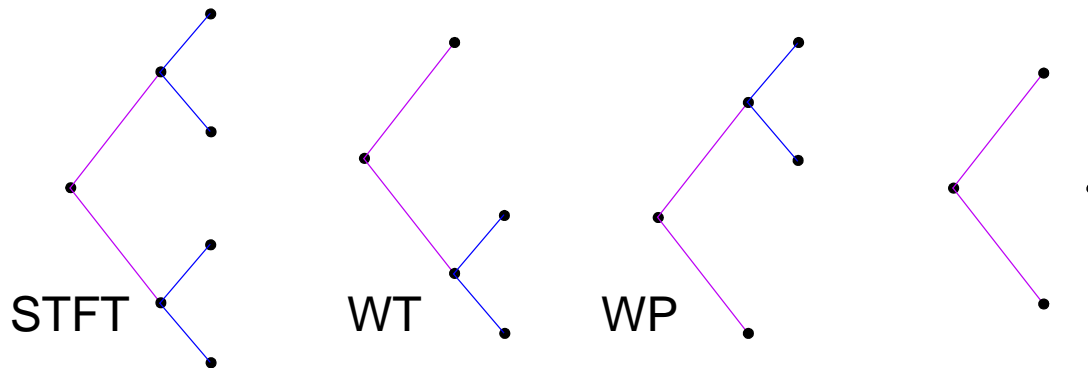
## Tree-structured filter banks

Easiest way  
to build  
multichannel  
filter banks

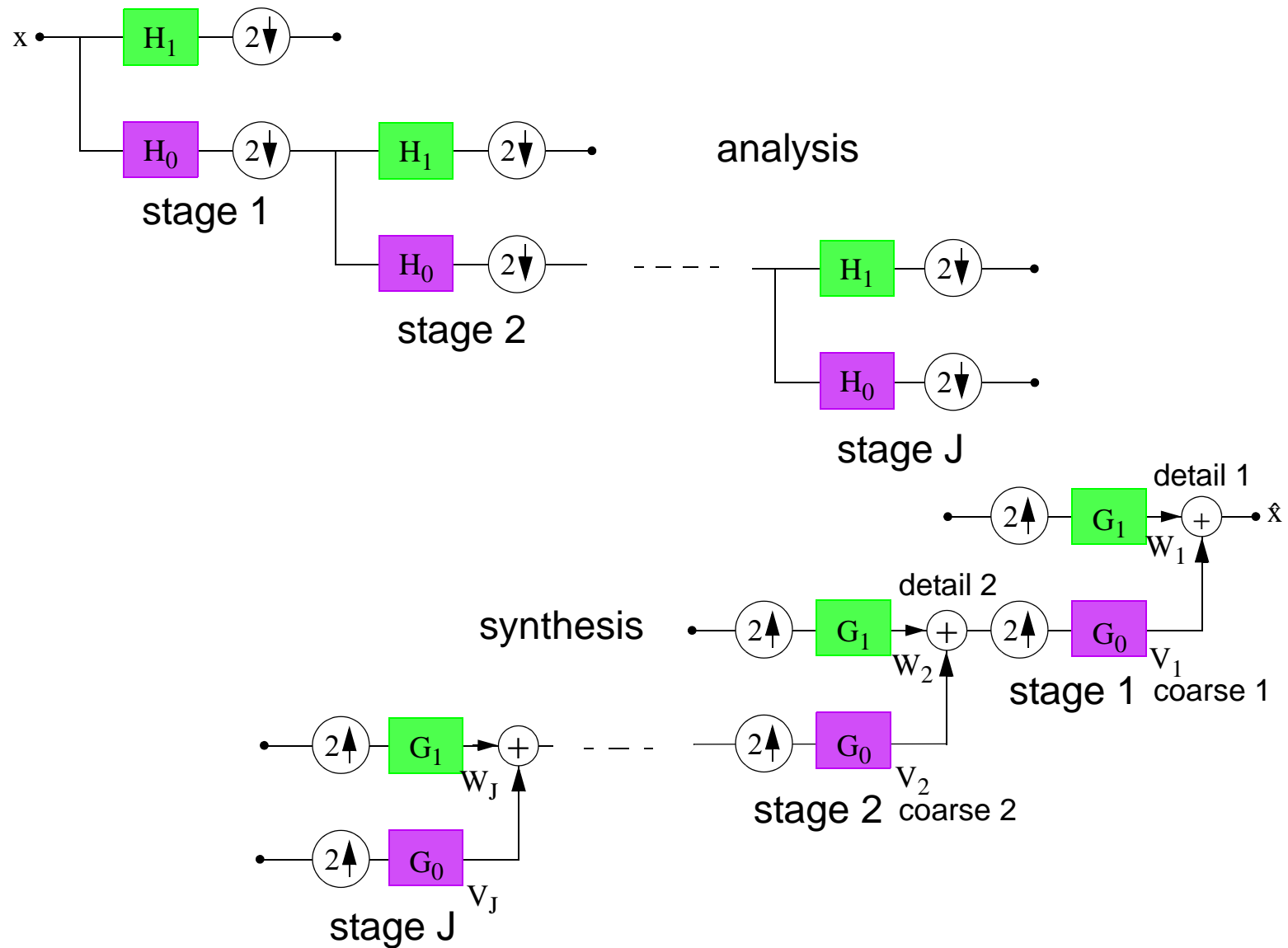
- DWT  
octave band
- wavelet  
packets



**Example:** All possible trees of depth two

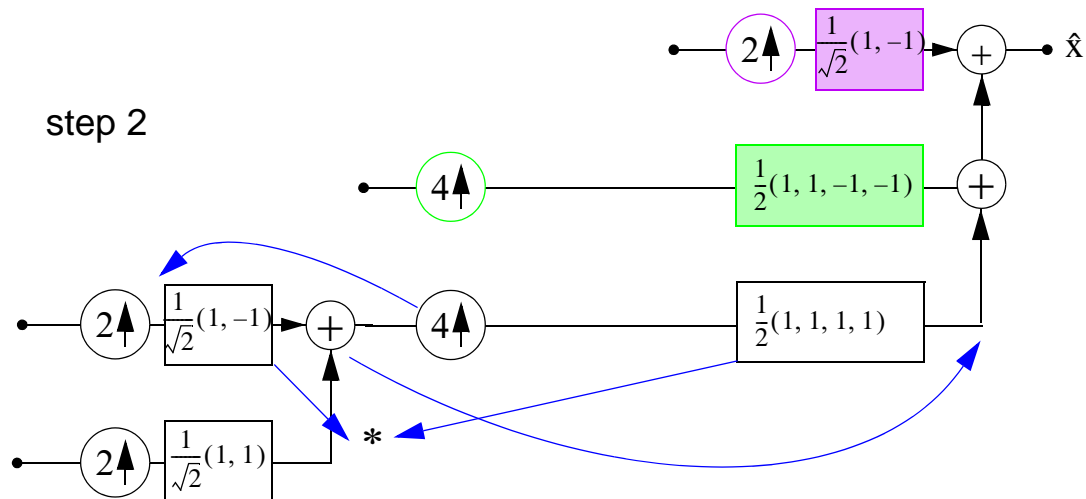
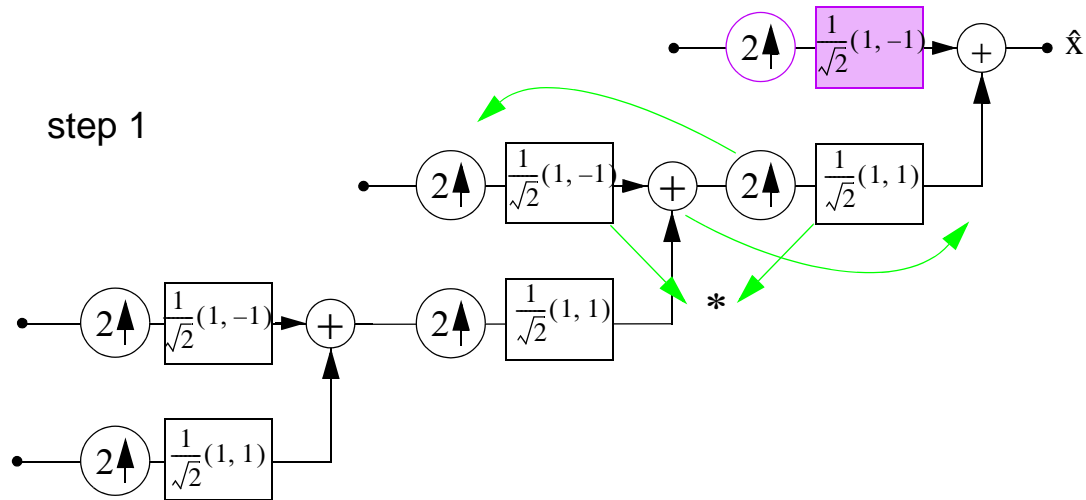


## DWT - Octave band filter banks



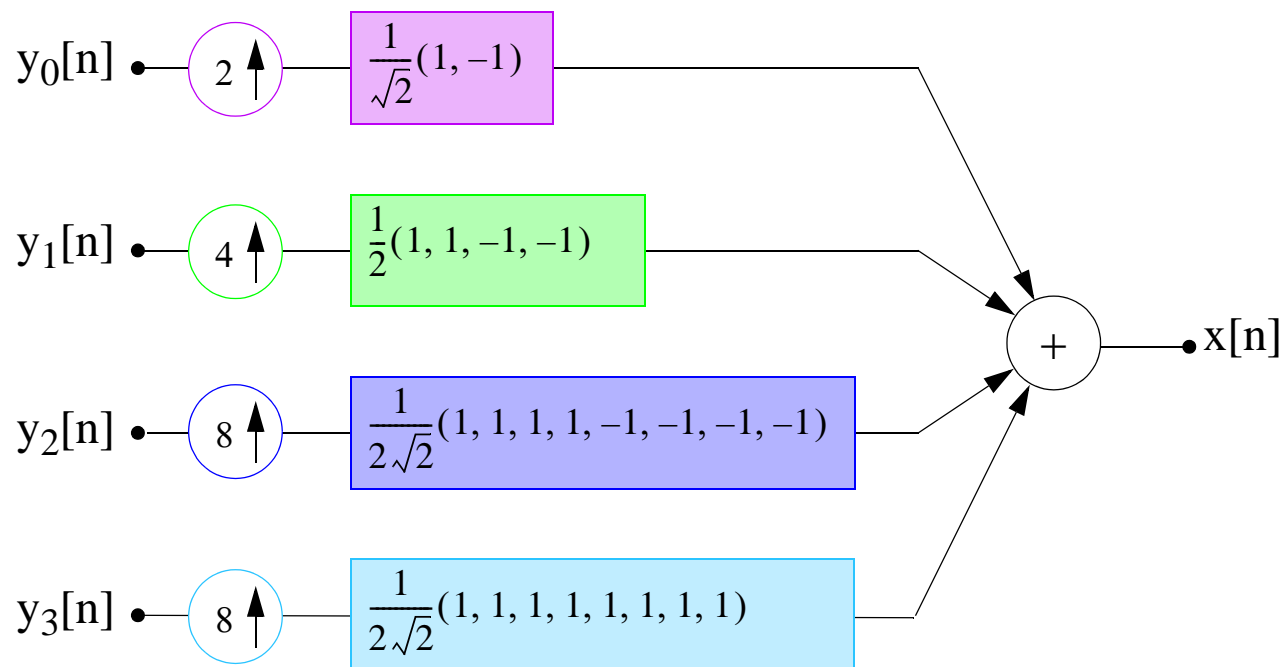
# DWT - Octave band filter banks...

## ... three stages with Haar filters



## DWT - Octave band filter banks...

### ... three stages with Haar filters



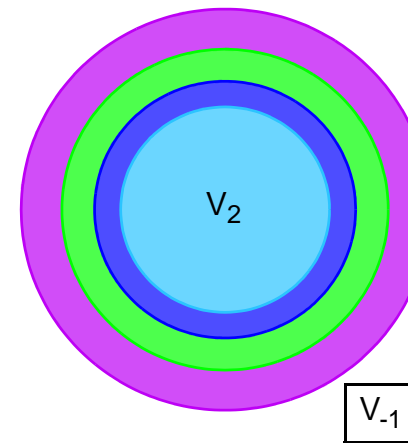
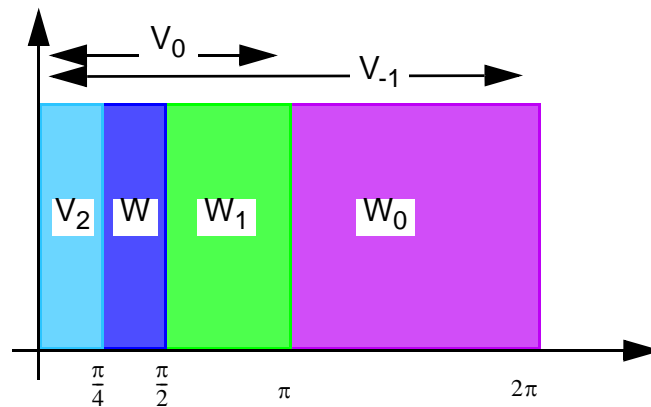
**Basis functions...**  
**... three stages with Haar filters**

$$\begin{bmatrix} 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \\ 1 & 1 & -1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & -1 & -1 \\ 1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \end{bmatrix}$$

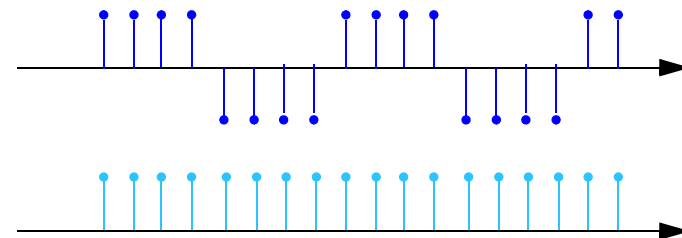
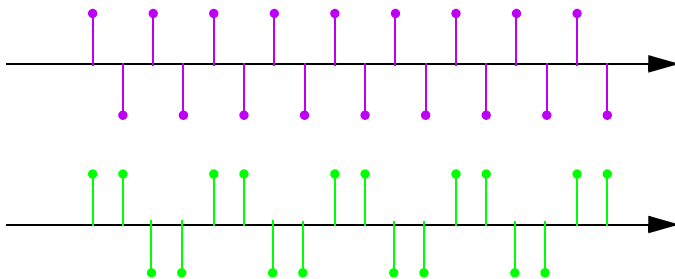
- we did not include scale factors  
to make rows of unit energy

## DWT - Octave band filter banks

Results in the discrete wavelet transform



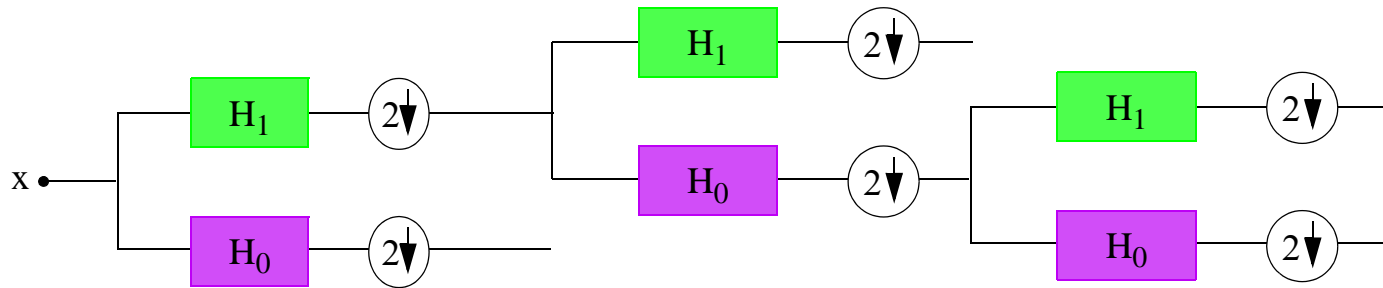
Basis functions



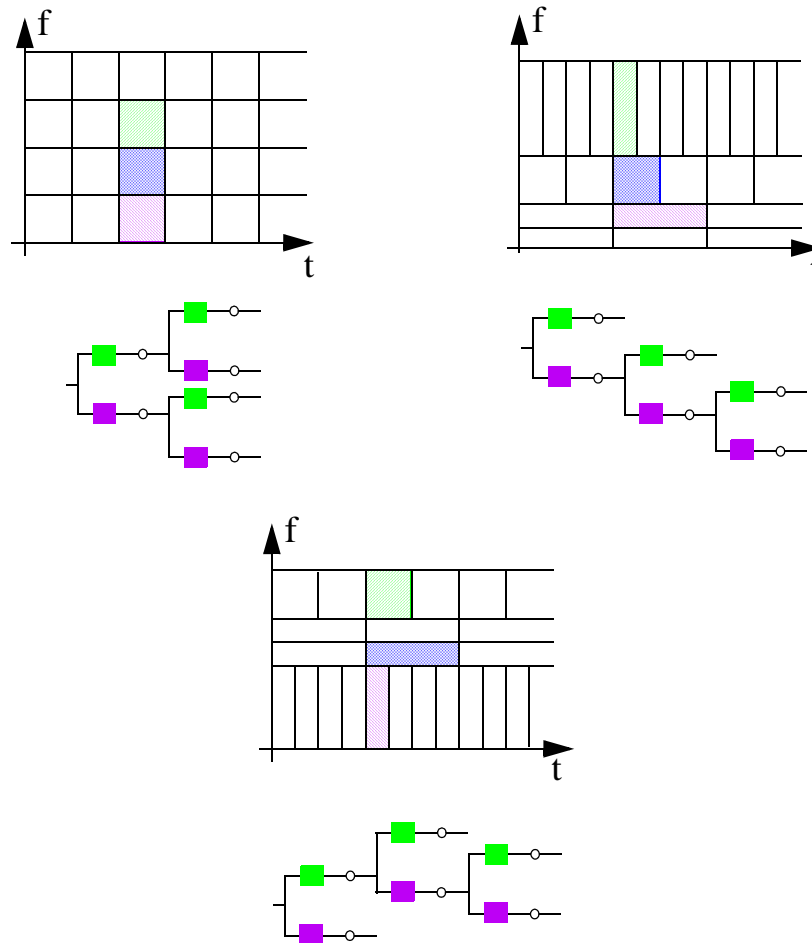


## Wavelet packets

Arbitrary tree: grows to fit the signal



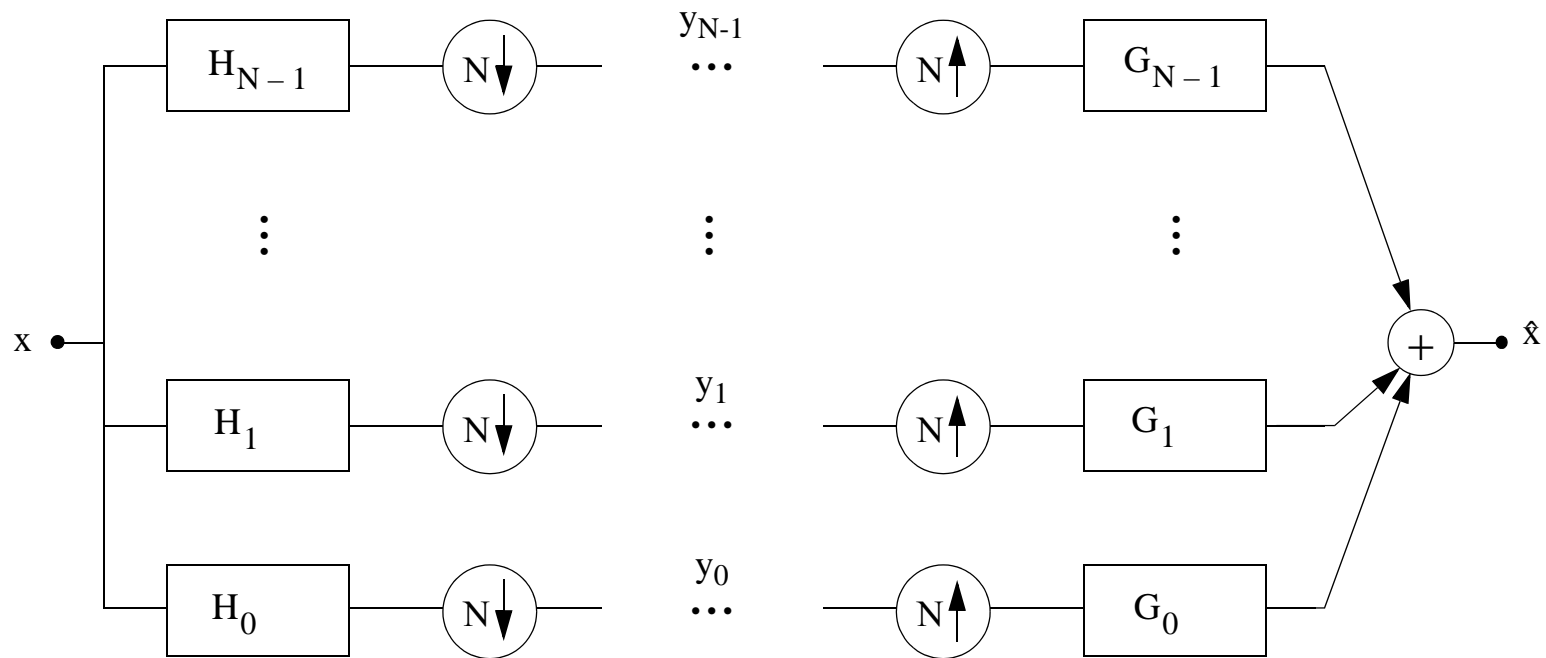
## Tree-structured filter banks ... ... time-frequency analysis



## Multichannel filter banks

[Vaidyanathan & Dogaanata]: **lattice structures**

- similar to the two-channel case
- complete factorization

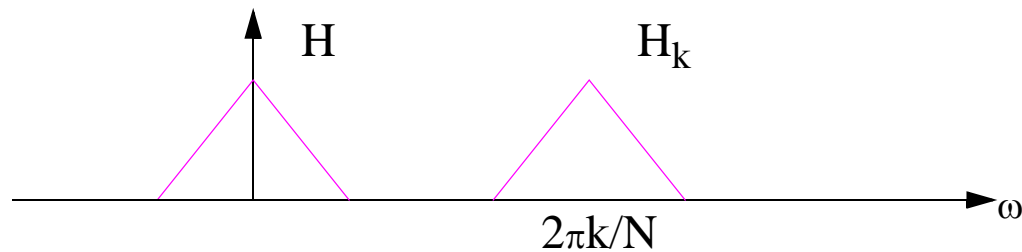


## Modulated filter banks

All filters derived from one prototype by modulation

$$H_k(z) = H(W_N^k z)$$

$$h_k[n] = \left\{ h[0], W_N^{-k} h[1], W_N^{-2k} h[2], W_N^{-3k} h[3], \dots \right\}$$

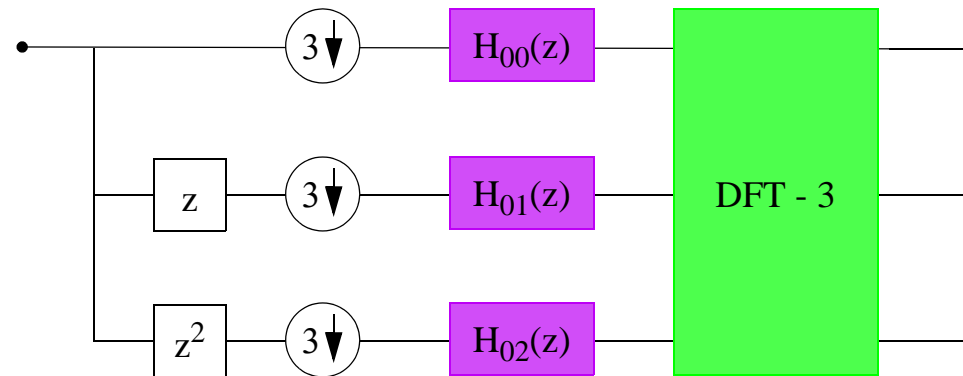


Polyphase matrix has a particular form (ex.  $N=3$ )

$$\begin{bmatrix} H_0 & H_1 & H_2 \\ H_0 W^{-1} & H_1 W^{-1} & H_2 W^{-1} \\ H_0 W^{-2} & H_1 W^{-2} & H_2 W^{-1} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & W^{-1} & W^{-2} \\ 1 & W^{-2} & W^{-1} \end{bmatrix} \cdot \begin{bmatrix} H_0 & 0 & 0 \\ 0 & H_1 & 0 \\ 0 & 0 & H_2 \end{bmatrix}$$

## Modulated filter banks

Implementation: polyphase filters + DFT



**Theorem:** [Discrete Balian-Low]

There are no FIR perfect reconstruction modulated filter banks with modulation by the roots of unity and critical sampling. In particular, there are no orthonormal solutions.

## **Local cosine bases ... ... answer to time-frequency problem**

### **How does one achieve locality in time and frequency?**

- solution: divide the axis into intervals and construct Fourier series on them

### **Problems**

- convergence slow and approximation poor
- discontinuity

### **How to divide the time axis?**

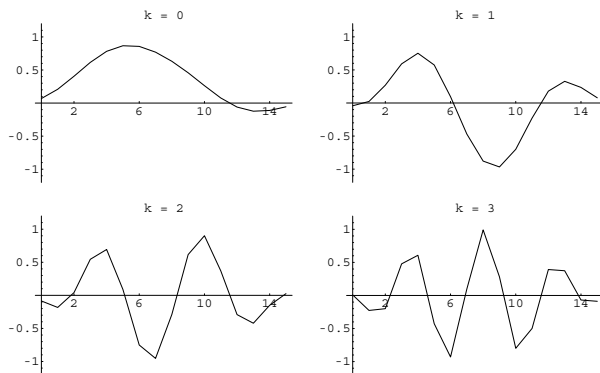
- improvement by local cosine bases
- discrete time: [Malvar, Princen, Bradley]
- continuous time: [Coifman & Meyer]
- smooth extension so that the functions overlap but with folding that guarantees orthogonality

## Local cosine bases ... ... in discrete time

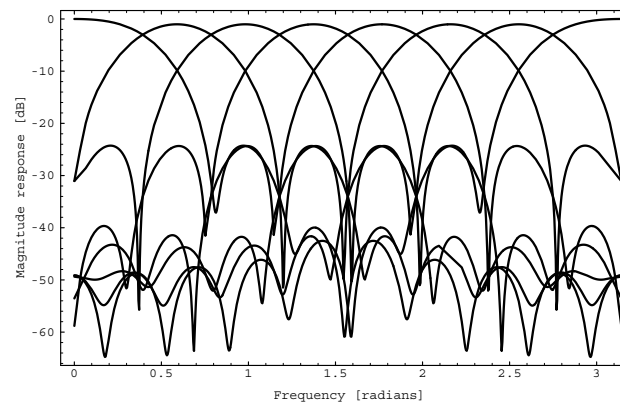
**Filters: modulated prototype filter**

$$h_k[n] = w[n] \times \cos\left(\frac{2\pi(2k+1)}{4N}\left(n - \frac{2N-1}{2}\right) + \frac{\pi}{4} + \frac{k\pi}{2}\right)$$

impulse responses

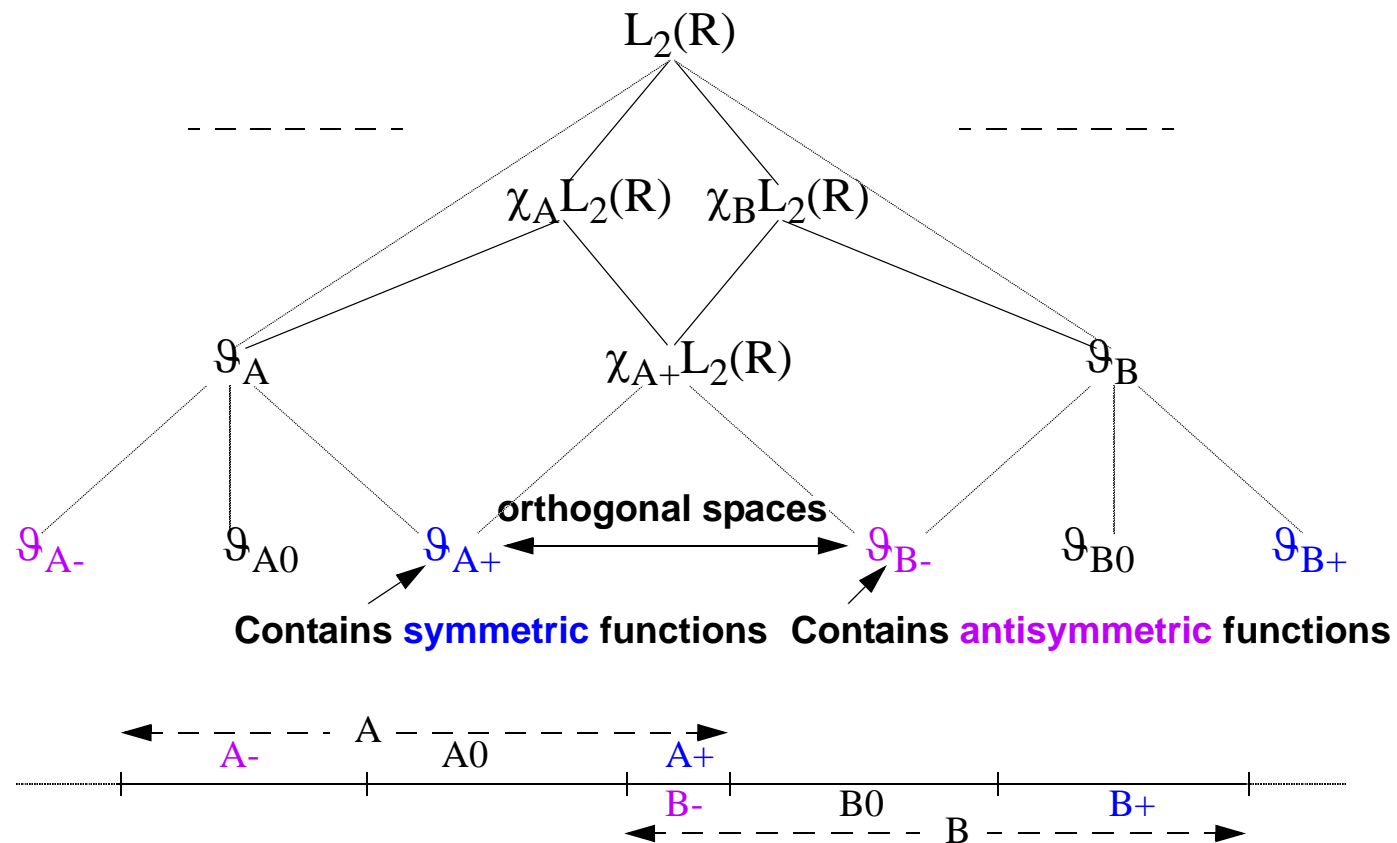


magnitude responses



## Local cosine bases ... ... why does it actually work?

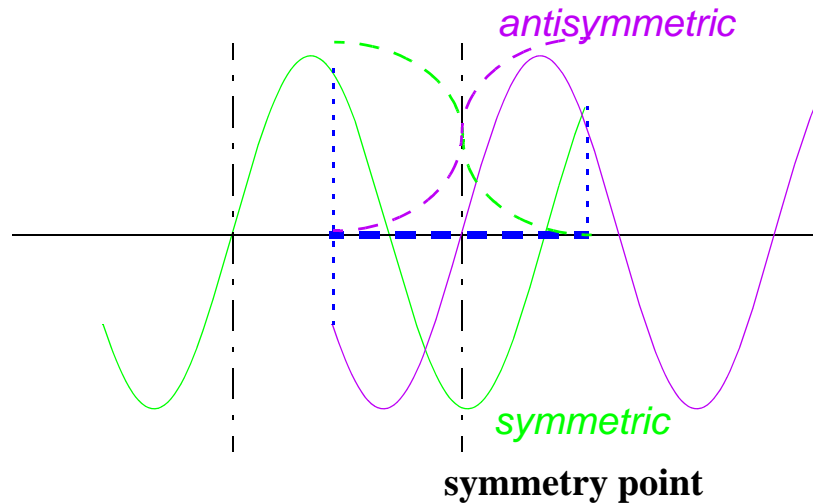
Reformulate the problem [Bernardini & Kovacevic]



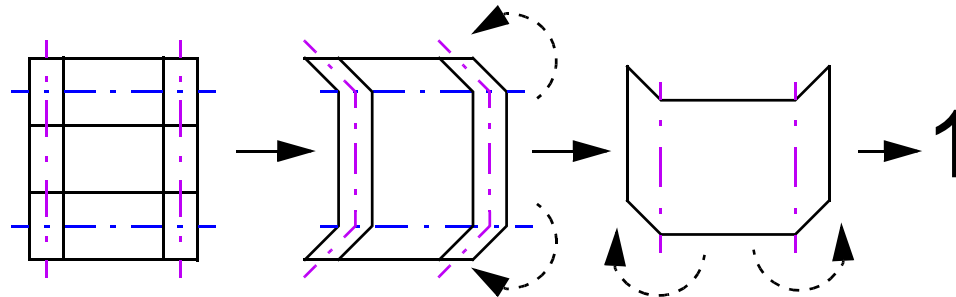


## Local cosine bases

Orthogonality of two subspaces  $\mathcal{G}_{A+}$  and  $\mathcal{G}_{B-}$



- use projections to build functions in subspaces
- window satisfies power-complementarity



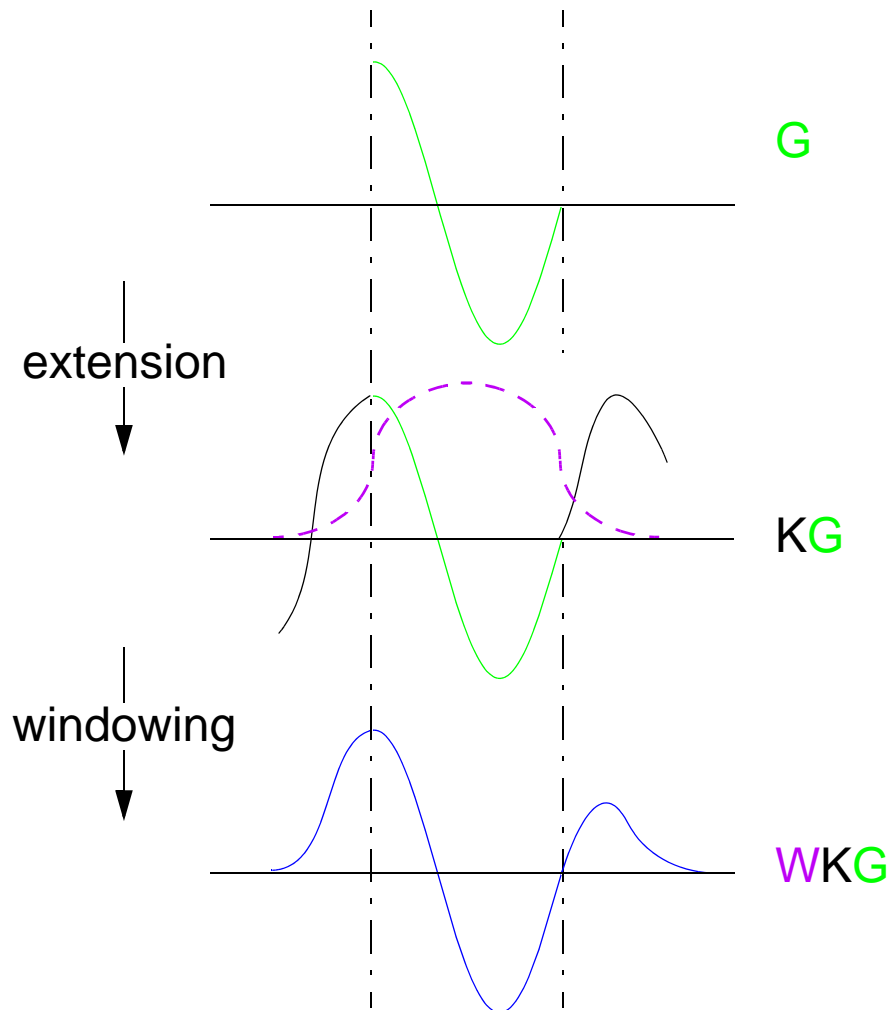
## Local cosine bases ... ... building the bases

**General structure of an  
orthonormal basis**

$$H = WKG$$

### Properties

- fast implementation
- one prototype filter
- can switch between different transforms
- any # of dimensions
- starting basis not necessarily cosine



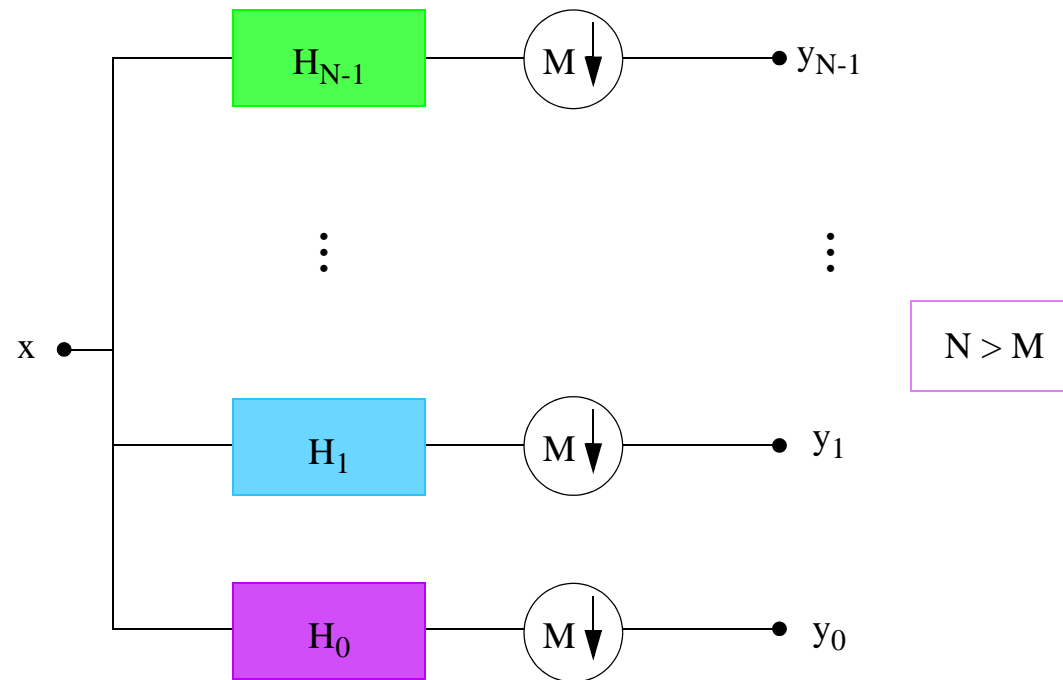
## Local orthogonal bases ... ... summary

- one prototype filter
- can switch between different transforms
- any # of dimensions
- flexible design tool
- design bases with prescribed properties
- complexity low

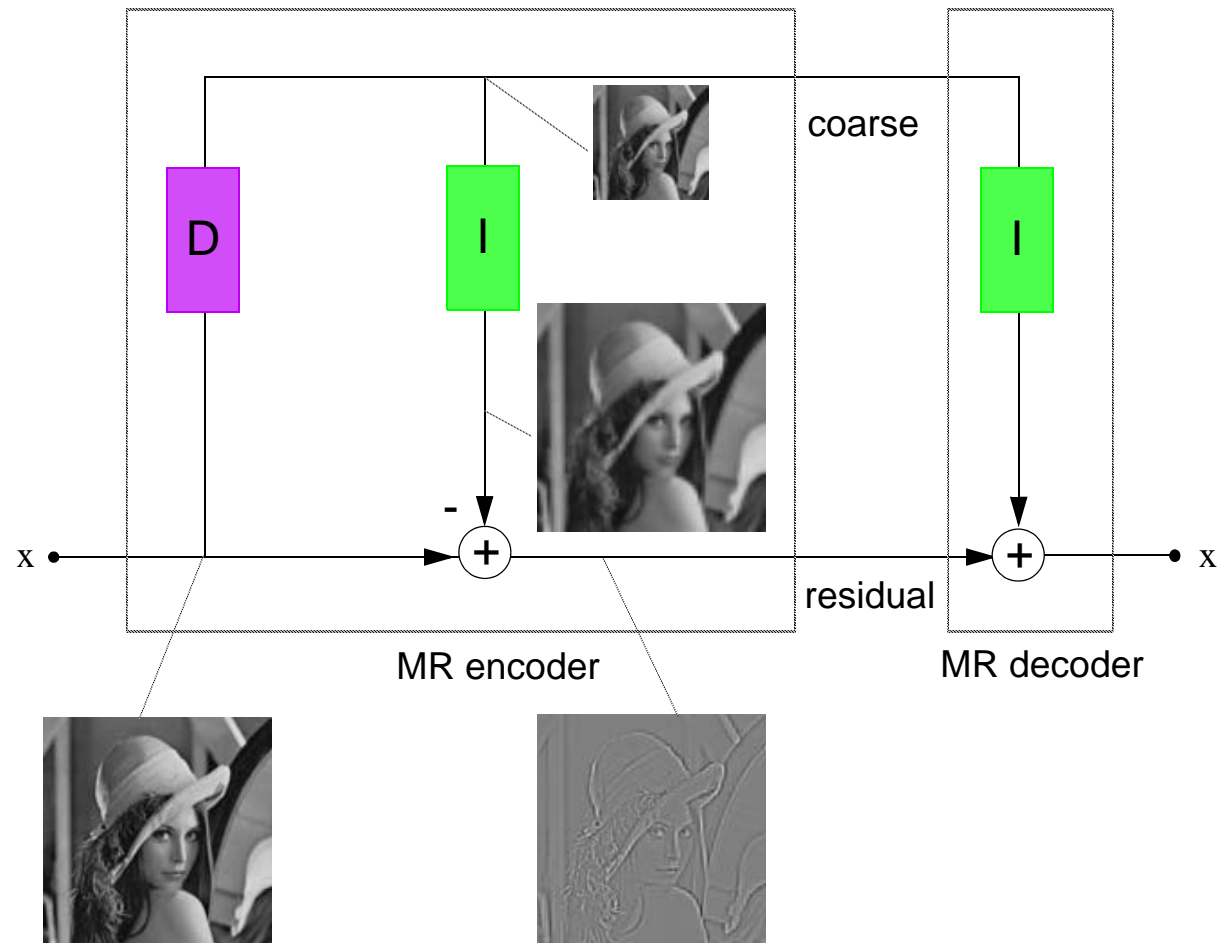
Previous		Local Orthogonal Bases		
$\mu$	$\alpha$		$\mu$	$\alpha$
256	248	W	32	/
		K	/	24
		G	64	56
256	248		96	80

- used in almost all standard audio coders

## Oversampled filter banks

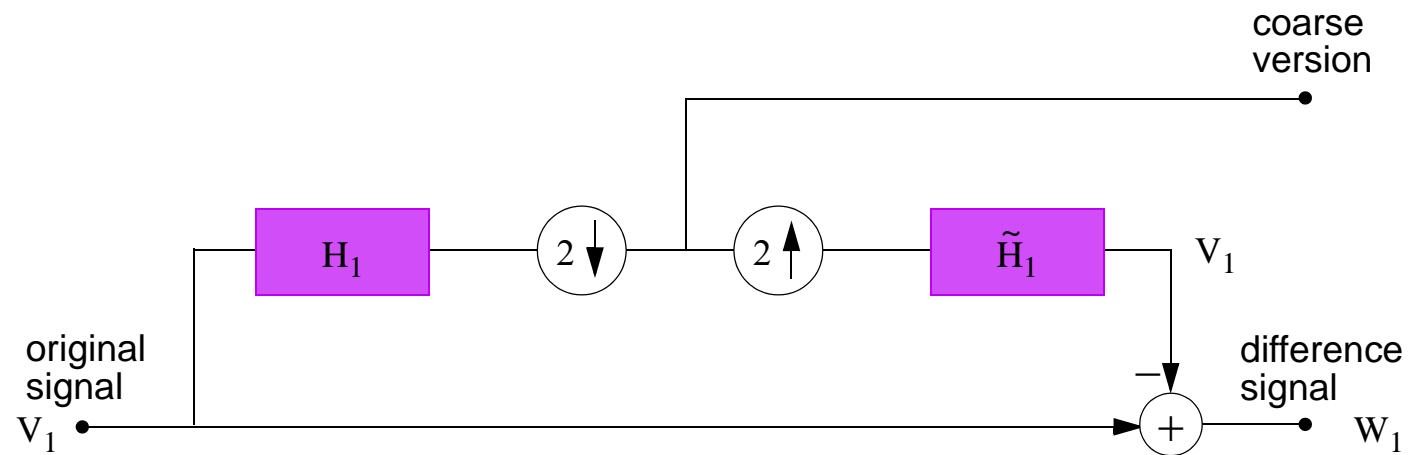


## Pyramid scheme



## Pyramid scheme

### Orthogonal filter used



### Advantages

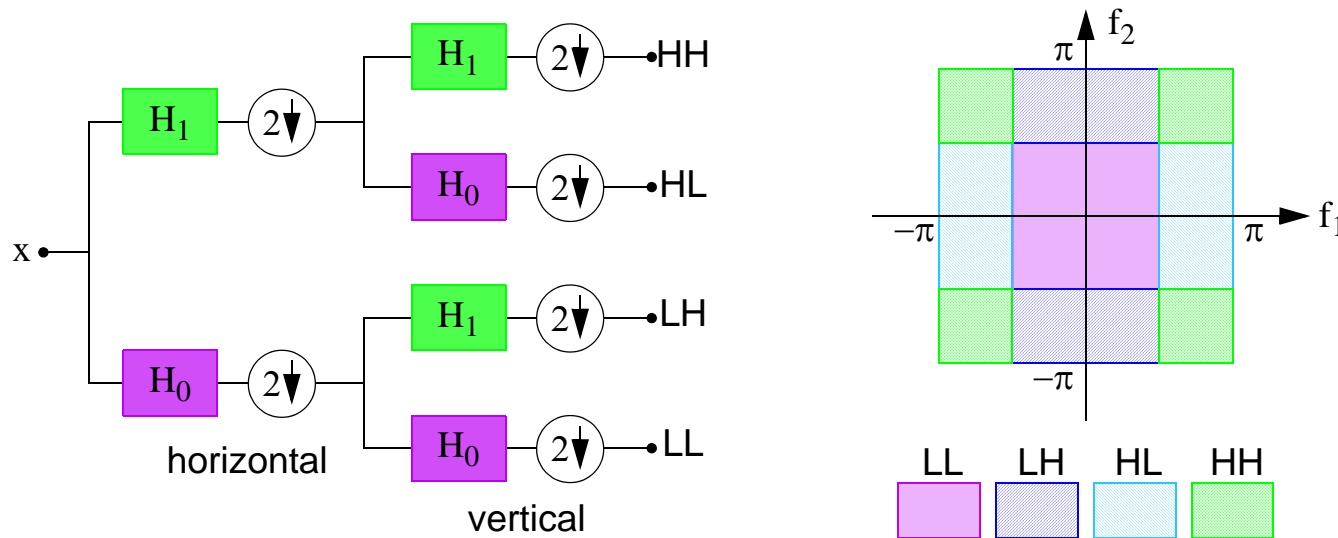
- robustness
- decimation and interpolation operators: arbitrary

### Drawbacks

- not critically sampled

## Multidimensional filter banks

**Main approach: use 1D techniques in a separable fashion**



### Problems

- very constrained filter design (separable filters)
- just rectangular spectrum divisions possible
- some solutions are not possible (ex. LP + ON)

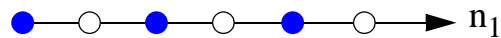
**Problem with MD: lack of factorization theorems**

## Multidimensional filter banks ... ... sampling

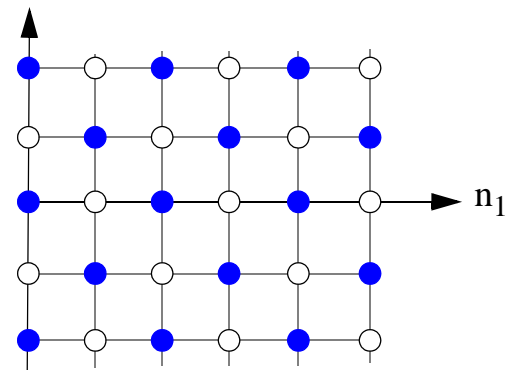
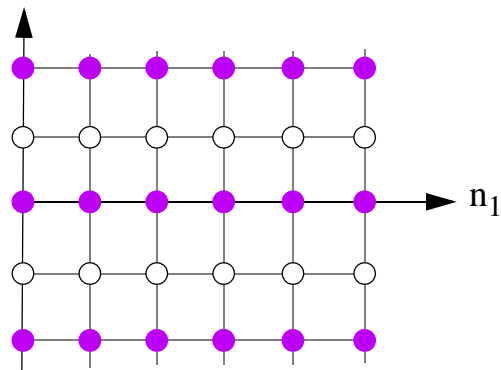
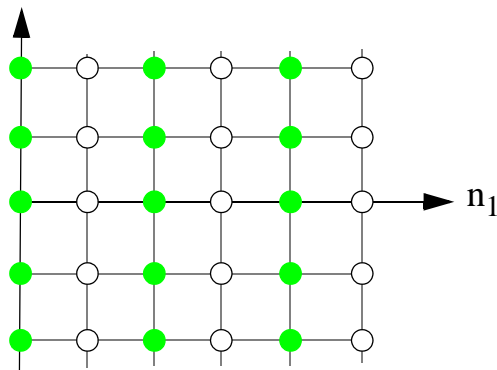
Main difference when compared to 1D:  
sampling represented by a lattice

To sample by 2:

- in 1D



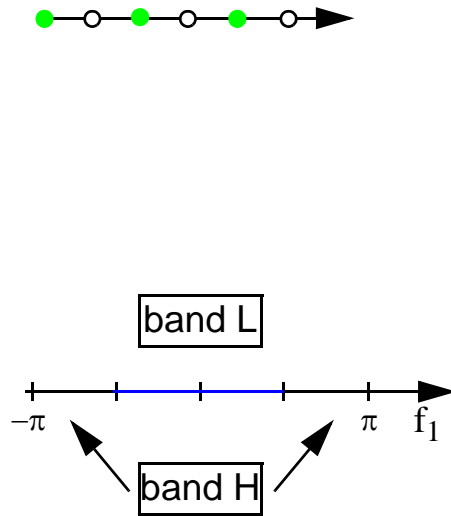
- in 2D



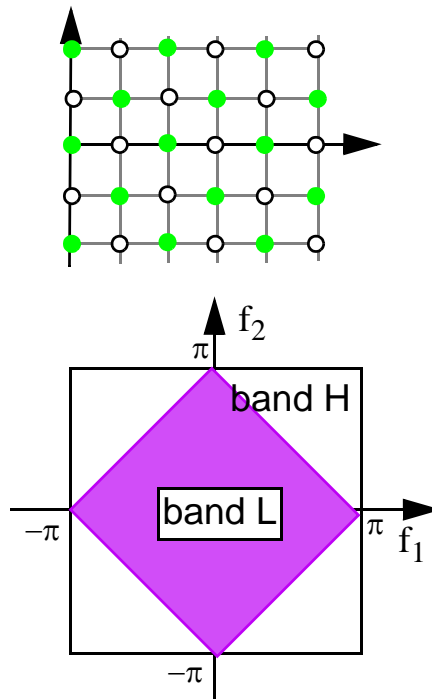


# Multidimensional filter banks ... two-channels

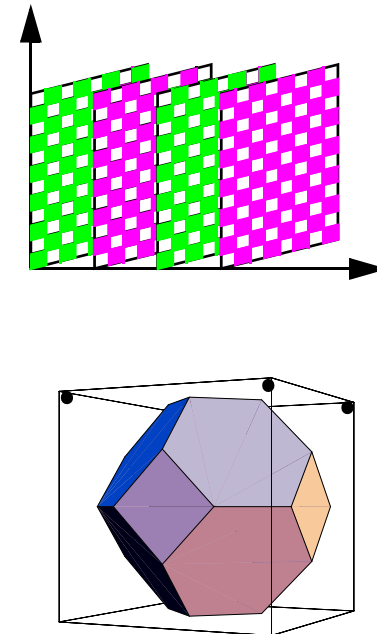
in 1D



in 2D

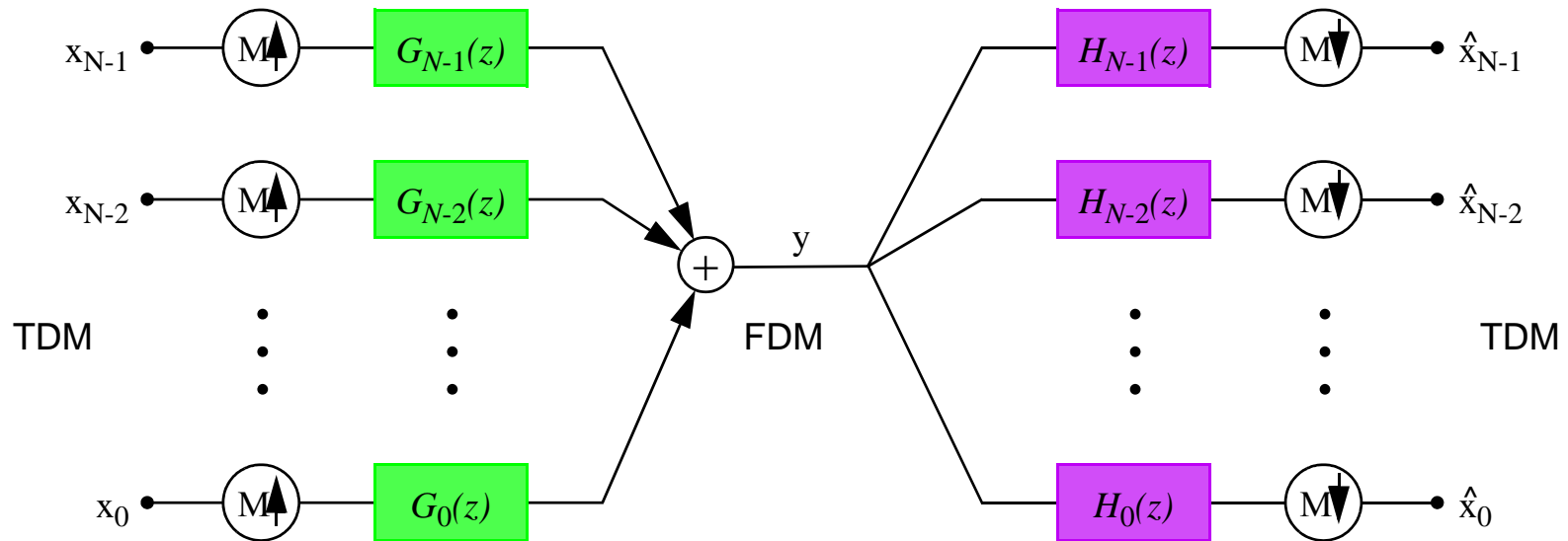


in 3D



# Transmultiplexers

Dual to filter banks: used in telecommunications



Analysis similar to that of filter banks